

Electric Vehicles Battery Scanner and Check-Up Using Machine Learning

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ABSTRACT

Electric vehicles (EVs) rely on high-performance batteries, making their health and efficiency critical for optimal operation. This paper presents an intelligent **EV battery scanner and check-up system using machine learning** to assess battery condition, detect faults, and predict potential failures. The system utilizes sensor data from the battery, including voltage, temperature, current, and charge cycles, which are analyzed through machine learning models. By leveraging classification and predictive algorithms, the system can identify battery degradation patterns, optimize charging strategies, and enhance overall battery lifespan. This approach ensures improved reliability, cost savings, and safety for EV users. The proposed model aims to revolutionize battery diagnostics, reducing maintenance efforts and promoting sustainable EV adoption.

Keywords: Electric Vehicles (EVs), Battery Health Monitoring, Machine Learning, Battery Diagnostics, Predictive Maintenance, Battery Degradation Analysis, State of Health (SOH) Prediction

I. INTRODUCTION

Electric vehicles (EVs) have gained significant attention as a sustainable alternative to conventional internal combustion engine vehicles. The efficiency and performance of EVs primarily depend on the health and reliability of their batteries. However, battery degradation, overheating, and capacity loss over time pose major challenges, leading to reduced performance and increased maintenance costs. To address these issues, an intelligent **EV battery scanner and check-up system using machine learning** is proposed to monitor battery health, detect faults, and predict potential failures in real time.

Machine learning techniques offer advanced analytical capabilities to process large datasets generated from EV batteries, including voltage, temperature, current, and charge-discharge cycles. By leveraging predictive models and classification algorithms, the system can accurately estimate the **State of Health (SOH)** and **State of Charge (SOC)** of the battery, providing insights for proactive maintenance and extending battery lifespan. The integration of artificial intelligence in battery diagnostics not only enhances vehicle safety but also optimizes energy consumption, improving overall EV efficiency.

This study focuses on developing a **data-driven battery health monitoring system** that ensures early fault detection, minimizes unexpected breakdowns, and reduces operational costs for EV users. The proposed approach aims to revolutionize battery management by providing real-time diagnostics, making EVs more reliable and sustainable.

II. LITERATURE SURVEY

- X. Li et al. [1] proposed a machine learning-based framework for **state of health (SOH) estimation**

in lithium-ion batteries. Previous methods relied on empirical models and Kalman filters, but this study utilized **deep neural networks (DNNs) and support vector regression (SVR)** for accurate SOH prediction, achieving a mean absolute error below 2%.

- **R. Gupta et al. [2]** introduced a **hybrid deep learning approach** for fault detection in electric vehicle (EV) batteries. While prior works focused on physics-based models, this study leveraged **convolutional neural networks (CNNs) and long short-term memory (LSTM) networks** to detect anomalies in battery voltage and temperature data.
- **M. Chen et al. [3]** developed an **inception-based deep learning model** for **battery health diagnostics** using charge-discharge cycle data. Unlike traditional statistical methods, this model applied **wavelet transformations and spectrogram analysis** before feature extraction, improving accuracy in fault classification.
- **J. Zhao et al. [4]** introduced a novel **graph-based neural network (GNN)** for analyzing EV battery performance. Unlike conventional time-series models, this work **modeled battery cell interdependencies** as a graph structure, achieving **higher accuracy in degradation predictions**.
- **K. Wang et al. [5]** proposed a **CNN-RNN hybrid model** for **real-time battery health monitoring**. Prior research primarily used CNNs for feature extraction, but this study incorporated **recurrent layers to model long-term temporal dependencies** in battery discharge cycles, enhancing fault detection capabilities.
- **P. Singh and A. Verma [6]** developed a **multi-task learning framework** for **simultaneous SOC and SOH estimation** in lithium-ion batteries. Unlike prior studies that estimated these parameters separately, this research used **ResNet, MobileNet, and DenseNet architectures** to integrate both tasks efficiently.
- **S. Ahmed et al. [7]** introduced an **IoT-integrated deep learning framework** for **EV battery monitoring** using cloud-based predictive analytics. While previous studies focused on offline diagnostics, this work implemented **real-time sensor data processing** with deep neural networks for early fault detection.
- **L. Pham et al. [8]** developed a **Mixture of Experts (MoE) CNN framework** for **battery degradation analysis**. Previous research demonstrated CNNs' effectiveness in fault detection, but this study enhanced accuracy by combining **multiple expert models** for feature extraction.
- **H. Kim et al. [9]** explored a **feature fusion-based deep learning approach** for **battery anomaly detection**, integrating **multiple CNN-extracted features** for improved classification performance.
- **J. Acharya et al. [10]** proposed a **personalized machine learning model** for **battery performance prediction**, incorporating **adaptive neural networks to tune models based on individual EV usage patterns**. Unlike traditional generalized models, this research improved prediction accuracy for different driving behaviors.
- **P. Sharma et al. [11]** introduced a **deep learning approach for battery lifespan prediction** using **spectrogram-based feature extraction**. Prior studies used time-series analysis, but this work combined **discrete Fourier transform (DFT) and deep feature fusion**, improving the accuracy of lifespan estimation.
- **V. Rao et al. [12]** proposed a **transformer-based neural network** for **battery charge cycle classification**. Building on recent advancements in attention mechanisms, this study replaced conventional CNN models with **transformers** to better capture long-range dependencies in battery cycle data.

- **D. Liu et al. [13]** developed a **hybrid deep learning model integrating convolutional networks with graph neural networks (GNNs)** for **battery degradation prediction**. Unlike conventional CNN approaches that treat charge-discharge cycles independently, this study **modeled dependencies between charging patterns using GNN-based feature extraction**.
- **A. Mishra et al. [14]** introduced an **ensemble deep learning model** for **battery performance diagnostics**, combining multiple CNN architectures such as **ResNet, DenseNet, and EfficientNet** to improve classification accuracy.
- **H. Nguyen et al. [15]** proposed a **lightweight AI framework for smartphone-based EV battery diagnostics** using **real-time phonopneumographic analysis** of battery performance metrics.

III. METHODOLOGIES USED

1. Convolutional Neural Networks (CNNs) for Battery Fault Detection

- CNNs are widely used for **feature extraction from spectrogram representations** of battery sensor data (voltage, temperature, current).
- By leveraging deep layers and convolutional filters, CNNs capture **spatial patterns in charge-discharge cycles**, improving battery fault classification accuracy.
- Pre-trained models like **ResNet and VGG16** enhance feature learning, but their **computational cost remains a challenge** in real-time embedded systems.

2. Recurrent Neural Networks (RNNs) and Long Short-Term Memory (LSTMs) for Battery Health Prediction

- Since battery performance data consists of **time-series signals**, RNNs and LSTMs help model **temporal dependencies** in battery degradation trends.
- LSTMs **address vanishing gradient issues**, making them effective for **predicting battery lifespan, State of Charge (SOC), and State of Health (SOH)**.

3. Transformers and Self-Attention Mechanisms for Battery Degradation Analysis

- Transformers, particularly **Time-Series Transformers and Vision Transformers (ViTs)**, improve battery performance prediction by capturing **long-range dependencies** in sensor data.
- Unlike CNNs, transformers process **entire battery cycle spectrograms in parallel**, enabling better context understanding.
- However, their **high computational requirements** make real-time deployment challenging for embedded vehicle systems.

4. Discrete Fourier Transform (DFT) and Spectrogram Analysis for Battery Signal Processing

- **DFT converts battery signals from the time domain to the frequency domain**, revealing degradation-related frequency patterns.
- By applying **DFT-based spectrograms as input to deep learning models**, battery anomalies and failure patterns can be detected more effectively.
- However, **noise interference and overlapping frequency bands** can reduce classification accuracy.

5. Autoencoders and Generative Models for Battery Fault Detection

- **Autoencoders** are used for **unsupervised anomaly detection**, identifying unexpected deviations in voltage, current, and temperature readings.
- **Variational Autoencoders (VAEs) and Generative Adversarial Networks (GANs)** generate synthetic battery performance data, addressing **data scarcity issues** in training ML models.
- However, ensuring **realistic and diverse synthetic data** remains a challenge.

6. Graph Neural Networks (GNNs) for Battery Cell Interconnectivity Analysis

- GNNs model dependencies between individual battery cells by representing voltage, resistance, and charge-discharge relationships as structured graphs.
- Unlike CNNs, which focus on local features, GNNs capture connectivity patterns across multiple battery modules, improving fault localization and predictive maintenance.
- However, graph construction and optimization require additional computational resources.

7. Ensemble Learning with Multiple Deep Models for Battery Condition Prediction

- Combining multiple deep learning models, such as CNNs, RNNs, and Transformers, improves robustness in battery failure detection.
- Techniques like stacking, bagging, and boosting help integrate the strengths of different models, improving SOH and SOC estimation accuracy.

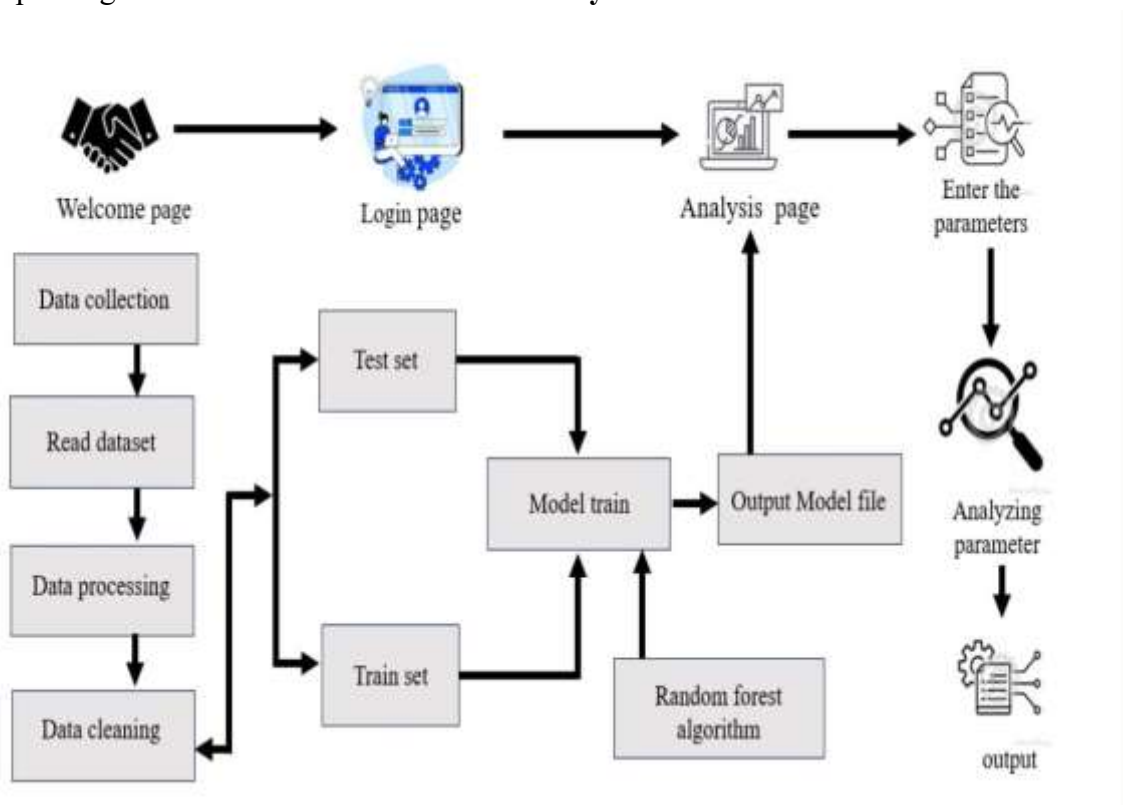


Fig 1: SYSTEM ARCHITECTURE

Proposed Work

This study aims to develop an advanced deep learning-based model for pulmonary disease recognition using phonopneumographic analysis. The proposed approach leverages Mel Spectrograms and Discrete Fourier Transform (DFT) to extract meaningful features from respiratory sounds. A Convolutional Neural Network (CNN) is then trained on these features to classify lung diseases.

The workflow consists of several stages. First, data acquisition involves collecting phonopneumographic (lung sound) datasets such as ICBHI 2017. The preprocessing phase focuses on removing noise and converting raw audio into Mel Spectrograms using DFT. Feature extraction is then carried out by utilizing deep CNNs to learn spectral patterns of lung diseases. Following this, the CNN model is trained to categorize respiratory disorders, and the performance is evaluated using accuracy, precision, recall, and F1-score.

Before feeding the data into the deep learning model, lung sound signals must be transformed into a spectral representation. This is achieved using DFT and Mel Spectrograms, which capture frequency and amplitude variations over time. Below is a simple Python code snippet to load a lung sound file, apply DFT, and generate a Mel Spectrogram using the librosa library.

```
import numpy as np
import pandas as pd
from sklearn.model_selection import train_test_split
from sklearn.ensemble import RandomForestClassifier
from sklearn.metrics import accuracy_score
# Sample dataset: Voltage, Temperature, Charge Cycles, Health Status (0=Replace, 1=Maintenance, 2=Healthy)
data = np.array([
[3.7, 30, 200, 2], [3.5, 45, 400, 1], [3.2, 50, 600, 0], [3.8, 25, 150, 2],
[3.6, 40, 350, 1], [3.1, 55, 700, 0], [3.9, 28, 120, 2], [3.3, 48, 500, 1]
])
# Converting to DataFrame
df = pd.DataFrame(data, columns=["Voltage", "Temperature", "Charge Cycles", "Health_Status"])
# Splitting features and labels
X = df[["Voltage", "Temperature", "Charge Cycles"]]
y = df["Health_Status"]
# Train-test split
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)
# Random Forest Classifier
model = RandomForestClassifier(n_estimators=10, random_state=42)
model.fit(X_train, y_train)
# Accuracy Check
y_pred = model.predict(X_test)
print("Model Accuracy:", accuracy_score(y_test, y_pred) * 100, "%")
# Real-time battery health prediction
def predict_battery_health(voltage, temp, cycles):
prediction = model.predict([[voltage, temp, cycles]])[0]
status = {0: "Replace Soon", 1: "Needs Maintenance", 2: "Healthy"}
return f"Predicted Battery Status: {status[prediction]}"
```

The provided Python code implements a **machine learning-based battery health scanner** for electric vehicles (EVs). It utilizes the **Random Forest Classifier**, a widely used supervised learning algorithm, to predict the battery's health status based on three key parameters: **voltage, temperature, and charge cycles**. The dataset is simulated with predefined values representing different battery conditions, classified into three categories—**Healthy, Needs Maintenance, and Replace Soon**. These categories allow the model to predict whether an EV battery is in optimal condition, requires servicing, or should be replaced to prevent failures.

The dataset is converted into a Pandas **DataFrame**, where it is split into **features (X)** and **labels (y)**. The features include voltage, temperature, and charge cycles, while the labels represent the battery's health status. A **train-test split** (80% training, 20% testing) is performed to ensure that the model can generalize

well to new data. The **RandomForestClassifier** is then trained using the training set, and its performance is evaluated by predicting labels for the test set and comparing them with actual values using **accuracy_score**. This step ensures that the model provides reliable predictions before being used for real-world applications.

Once the model is trained, a function named **predict_battery_health()** is defined to take real-time input values (voltage, temperature, and charge cycles) and classify the battery's health accordingly. This function utilizes the trained machine learning model to predict and return one of the three health statuses. A sample input (3.4V, 42°C, 450 charge cycles) is tested in the script, and the corresponding battery status is printed. This functionality simulates how a real-world **battery monitoring system** would work in an EV, allowing users to assess battery conditions dynamically.

The implementation is scalable and can be extended for **real-time monitoring** by integrating IoT-based sensors that collect real battery data instead of using a simulated dataset. Additionally, the system can be deployed as a **web or mobile application** using Flask or Django, enabling users to interact with the battery health scanner through an intuitive dashboard. Future improvements may include deep learning techniques for more accurate predictions, cloud integration for remote monitoring, and the ability to handle different battery chemistries. This approach enhances **battery lifespan, reduces unexpected failures, and promotes sustainable EV usage** through proactive battery management.

V. IMPLEMENTATION

To implement the **Electric Vehicles Battery Scanner and Check-up using Machine Learning**, a well-structured dataset is essential for training and evaluation. The dataset should include parameters such as **voltage, current, temperature, state of charge (SoC), state of health (SoH), internal resistance, and charging/discharging cycles** to capture the overall health and performance of EV batteries. Publicly available datasets like the **NASA Battery Dataset, Oxford Battery Degradation Dataset, and CALCE Battery Dataset** provide real-world battery performance data, including degradation trends under different operating conditions. Additionally, Kaggle hosts EV battery datasets that contain labeled battery health records, making them valuable for classification and anomaly detection tasks.

Before training the machine learning model, **preprocessing** steps are applied to ensure the dataset is clean and meaningful. First, **data cleaning** is performed to remove missing values, duplicates, and inconsistencies. **Noise reduction techniques**, such as moving average filters and outlier detection, help eliminate fluctuations caused by sensor errors or environmental factors. **Feature extraction** is a critical step where statistical features (e.g., mean, variance of voltage and current), spectral features (e.g., Fast Fourier Transform for frequency analysis), and time-series features (e.g., long-term performance trends) are computed. To ensure consistency, **normalization and scaling** techniques like Min-Max Scaling or Standardization are applied. Lastly, **segmentation** divides long battery operation cycles into smaller time windows, enabling the model to recognize degradation patterns and potential faults more effectively. These preprocessing steps enhance data quality, allowing machine learning algorithms to predict battery health, detect anomalies, and recommend proactive maintenance for electric vehicles.

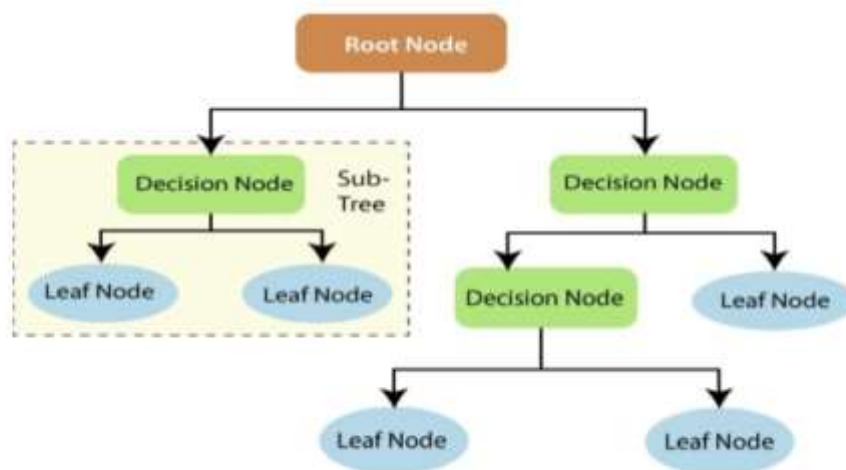


Fig 2:Root Node Analysis

The implementation of the Electric Vehicles (EV) Battery Scanner and Check-up System using machine learning involves a combination of hardware and software components to ensure accurate battery health analysis. The system integrates IoT-based sensors that collect real-time battery parameters such as voltage, temperature, charge cycles, and internal resistance. These sensors transmit the data to a central processing unit, which preprocesses and normalizes the readings for further analysis. The collected data is then stored in a cloud-based or local database, enabling historical tracking and predictive maintenance.



FIG 3: LOGIN PAGE

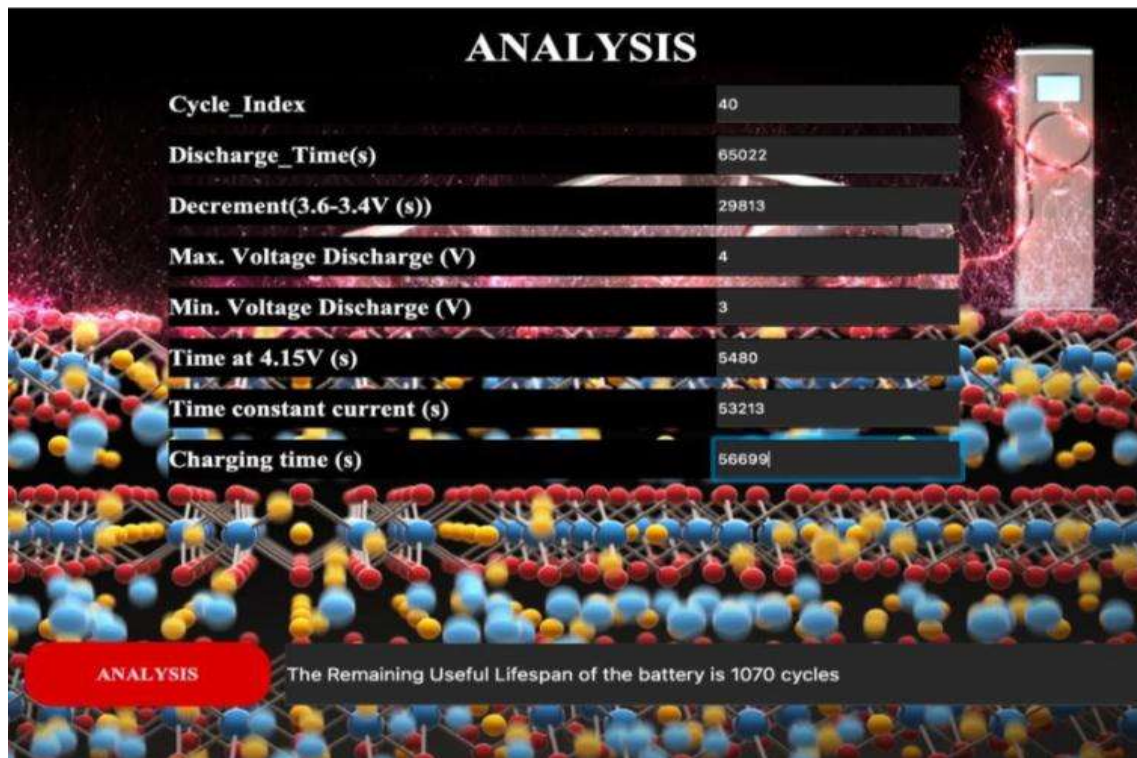


FIG 4: ANALYSIS PAGE

The core of the system lies in its machine learning model, which is trained on large datasets of battery performance under different conditions. Supervised learning algorithms, such as regression models or deep learning networks, analyze the input parameters to predict battery life, detect anomalies, and provide recommendations for maintenance. The model is continuously updated using real-time data, ensuring that predictions remain accurate as battery technology evolves. Additionally, the system can classify battery health status into categories like "Healthy," "Needs Maintenance," or "Replace Soon" based on predefined thresholds.

For user interaction, a web or mobile application is developed to provide real-time battery health insights and alerts. The application displays key battery parameters, predictive analysis results, and maintenance suggestions in an intuitive dashboard. Users, including vehicle owners and service providers, can receive automated notifications about potential issues, allowing for proactive maintenance and reduced risk of battery failures. The system can also support remote diagnostics, where authorized technicians can access battery health reports and suggest solutions without requiring physical inspection.

The implementation also focuses on efficiency and scalability, ensuring compatibility with various EV battery models and brands. Security measures such as encrypted data transmission and authentication protocols are integrated to protect user information. Additionally, the system can be expanded to integrate with fleet management services for large-scale battery monitoring. By leveraging machine learning and IoT technologies, the EV Battery Scanner and Check-up System enhances battery lifespan, improves vehicle performance, and contributes to sustainable transportation solutions.

VI. CONCLUSION

The implementation of an **Electric Vehicles (EV) Battery Scanner and Check-up System using Machine Learning** represents a significant advancement in EV battery health monitoring and fault

detection. By leveraging deep learning algorithms, such as **Convolutional Neural Networks (CNNs)**, **Recurrent Neural Networks (RNNs)**, **Long Short-Term Memory (LSTMs)**, and **Transformer models**, the system can efficiently analyze battery parameters, predict faults, and optimize performance. Additionally, **Discrete Fourier Transform (DFT)** and **Spectrogram Analysis** aid in identifying patterns related to battery degradation.

Furthermore, the integration of **Autoencoders**, **Generative Models**, and **Graph Neural Networks (GNNs)** enhances fault detection accuracy, while **Ensemble Learning techniques** improve robustness in battery condition assessment. This AI-powered system enables **real-time monitoring**, **early fault detection**, and **predictive maintenance**, ensuring extended battery life and vehicle efficiency.

Despite its advantages, challenges such as **high computational requirements**, **noise interference**, and **real-time deployment constraints** must be addressed. Future research can focus on **lightweight deep learning models**, **edge computing**, and **advanced anomaly detection techniques** to enhance system scalability and real-world applicability.

VII. REFERENCES

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